Estimating Lorenz Curve for Iran by Using Continuous L1 Norm Estimation

Bijan Bidabad

Keywords: L1 norm, Lorenz Curve, Continuous estimation, Income distribution

Abstract
In this paper, the L1 norm of continuous functions and corresponding continuous estimation of regression parameters are defined. The continuous L1 norm estimation problem of one and two parameters linear models in continuous case are solved. We proceed to use the functional form and parameters of probability distribution function of income to exactly determine the L1 norm approximation of the corresponding Lorenz curve of the statistical population under consideration. Iran family budget data were used to estimate income distribution for the period of 1362-1370.

1. Introduction
The skewness of income distribution is persistently exhibited for different populations and in different times. It is discussed that Pearsonian family distributions are rival functions to explain income distribution. Lorenz curve is a method to analyze the skew distributions. There is a relation between the area under the Lorenz curve and the corresponding probability distribution function of the statistical population (see, Kendall and Stuart (1977)). That is, when the probability distribution function is known, we may find the corresponding Gini coefficient as the measure of inequality.

Estimation of the Lorenz curve is confronted with some difficulties. For this estimation, we should define an appropriate functional form which can accept different curvatures (see, Bidabad and Bidabad (1989a,b)). There is another problem, that is, to create the necessary data set for estimating the corresponding parameters of the Lorenz curve, a large amount of computation on raw sample income data is inevitable. Obviously, these problems despite of their computational difficulties, make the significance of the estimated parameters poor (see, Bidabad and Bidabad (1989a,b)). To avoid this, we try to estimate the functional form of the Lorenz curve by using continuous information. In this paper we use the probability density function of population income to estimate the Lorenz function parameters. The continuous L1 norm smoothing method which will be developed for estimating the regression parameters is used to solve this problem.

---

1 Research professor of economics, Monetary and Banking Research Academy, Central Bank of Iran, Pasdaran, Zarakkhaneh, Tehran, 16619, Iran. bijan_bidabad@msn.com.
I should express my sincere thanks to Professor Yadolah Dodge from Neuchatel University of Switzerland who taught me many things about L1 norm when he was my Ph.D.dissertation advisor.
However, we concentrate on two rival probability density functions of Pareto and log-normal. Since, the former is simply integrable, there is no general problem to derive the corresponding Lorenz function and the function is uniquely derived. But in the latter case, the log-normal density function (which has better performance for full income range) than Pareto distribution (which better fits to higher income range, see, Cramer (1973), Singh and Maddala (1976), Salem and Mount (1974)), is not integrable and we can not determine its corresponding Lorenz function. In this regard we should solve the problem by defining a general Lorenz curve functional form and applying the L1 norm smoothing to estimate the corresponding parameters.

In this paper continuous L1 norm estimation is developed by using a similar method proposed in Bidabad (1987a,88a,89a,b) for discrete case. Then the method is applied to estimation of the Lorenz curve functional forms which have been proposed by Gupta (1984) and Bidabad and Bidabad (1989,92). At the end, we use our formulation to estimate Gini ratio and Kakwani length indices of inequality for the United States for the period of 1971-1990, based on the assumption that income is distributed log-normally.

2. L1 norm of continuous functions

Generally, Lp norm of a function f(x) (see, Rice and White (1964)) is defined by,
\[ ||f(x)||_p = \left( \int_{I} |f(x)|^p dx \right)^{1/p} \]  
(1)
Where, "I" is a closed bounded set. The L1 norm of f(x) is simply written as,
\[ ||f(x)||_1 = \int_{I} |f(x)| dx \]  
(2)

Suppose that the non-stochastic function \( f(x, \beta) \) of "x", is combined with stochastic disturbance term "u" to form y(x) as follows,
\[ y(x) = f(x, \beta) + u \]  
(3)
Where, \( \beta \) is unknown parameters vector. Rewriting u as the residual of y(x)-f(x,\beta), for L1 norm approximation of "\beta" we should find "\beta" vector such that the L1 norm of "u" is minimum. That is,
\[ \text{Min: } S = ||u||_1 = ||y(x)-f(x,\beta)||_1 = \int_{I} |y(x)-f(x,\beta)| dx \]  
(4)

3. Linear one parameter L1 norm continuous smoothing

Redefine f(x,\beta) as \( \beta x \) and y(x) as the following linear function,
\[ y(x) = \beta x + u \]  
(5)
Where, "\beta" is a single (non-vector) parameter. Expression (4) reduces to:
\[ \text{min: } S = ||u||_1 = ||y(x)-\beta x||_1 = \int_{I} |y(x)-f(x,\beta)| dx \]  
(6)

The discrete analogue of (6) is solved by Bidabad (1987a,88a,89a,b). In these papers we proposed applying discrete and regular derivatives to the discrete problem by using a slack variable "t" as a point to distinguish negative and positive residuals. A similar approach is used here to minimize (6). To do so in this case certain Lipschitz conditions are imposed on the functions involved (see, Usow (1967a)). Rewrite (6) as follows,
\[ \text{Min: } S = \int_{I} |x||y(x)/x - \beta| dx \]  
(7)
For convenience, define "I" as a closed interval [0,1]. The procedure may be applied to other intervals with no major problem (see, Usow (1967a), Hobby and Rice (1965), Kripke and Rivlin (1965)). To minimize this function we should first remove the absolute value sign of the
expression after the integral sign. Since "x" belongs to closed interval "I", y(x) (which is a linear function of "x") and also y(x)/x are smooth and continuous. Thus, since y(x)/x is uniformly increasing or decreasing function of "x", a value of tnl can be found to have the following properties,

\[
\begin{align*}
y(x)/x &< \beta & \text{if } x < t \\
y(x)/x &= \beta & \text{if } x = t \\
y(x)/x &> \beta & \text{if } x > t
\end{align*}
\] (8)

Value of the slack variable "t" actually is the border of negative and positive residuals. If value of "t" were known, from (8) (middle equation) we could calculate optimal value of "\beta" or inversely. But nor "t" neither "\beta" are known. To solve this problem, according to (8), we can rewrite (7) as two separate definite integrals with different upper and lower bounds.

\[
\begin{align*}
\min: S &= -\int_0^t |x| (y(x)/x - \beta)dx + \int_t^1 |x| (y(x)/x - \beta)dx \\
\beta
\end{align*}
\] (9)

Decomposition of (7) into (8) has been done by use of the slack variable "t". Since both "\beta" and "t" are unknown, to solve (9), we partially differentiate it with respect to "t" and "\beta" variables.

\[
\frac{\delta S}{\delta t} = \int_0^1 |x| dx - \int_t^1 |x| dx = 0
\] (10)

Using Liebniz' rule to differentiate the integrals with respect to their variable bounds "t", yields,

\[
\frac{\delta S}{\delta t} = -|t| \left[\frac{y(t)}{t} - \beta\right] - |t| \left[\frac{y(t)}{t} - \beta\right] = 0
\] (11)

Since "x" belongs to [0,1], equation (10) can be written as,

\[
\begin{align*}
\int_{0}^{t} x dx - \int_{t}^{1} x dx = 0 \\
\frac{1}{2} t^2 - \frac{1}{2} + \frac{1}{2} = 0
\end{align*}
\] (12)

or,

\[
\frac{1}{2} t^2 - \frac{1}{2} = 0
\] (13)

Which yields,

\[
t = \sqrt{2}/2
\] (14)

Substitute for "t" in equation (11), yields,

\[
\beta = \frac{y(\sqrt{2}/2)}{\sqrt{2}/2}
\] (15)

Remember that y(t) is function y(x) evaluated at x=t. Value of "\beta" given by (15) is the optimal solution of (6). The above procedure actually is generalization of Laplace weighted median for continuous case.

Before applying this procedure to Lorenz curve, let us develop the procedure for the two parameters linear model.

4. Linear two parameters \( L_1 \) norm continuous smoothing

Now, we try to apply the above technique to the linear two parameters model. Rewrite (4) as,

\[
\text{Min: } S = \|u\|_1 = \|y(x)-\alpha-\beta x\|_1 = \int_{x=1} |y(x)-\alpha-\beta x| dx
\] (16)

\[\alpha, \beta\]
Where, "\(a\)" and "\(\beta\)" are two single (non-vector) unknown parameters and \(y(x)\) and "\(x\)" are as before. According to Rice (1964c), let \(f(a*,\beta*,x)\) interpolates \(y(x)\) at the set of canonical points \(\{x_i;i=1,2\}\), if \(y(x)\) is such that \(y(x)-f(a*,\beta*,x)\) changes sign at these \(x_i\)'s and at no other points in \([0,1]\), then \(f(a*,\beta*,x)\) is the best \(L_1\) norm approximation to \(y(x)\) (see also, Usow (1967a)). With the help of this rule, if we denote these two points to \(t_1\) and \(t_2\) we can rewrite (16) for \(l=[0,1]\) as,

\[
S = \int_0^1 [y(x)-\alpha-\beta x]dx - \int_{t_1}^{t_2} [y(x)-\alpha-\beta x]dx + \int_{t_2}^1 [y(x)-\alpha-\beta x]dx
\]

(17)

Since \(t_1\) and \(t_2\) are also unknowns, we should minimize \(S\) with respect to \(\alpha, \beta, t_1\) and \(t_2\). Taking partial derivative of (17) using Liebniz' rule with respect to these variables and equating them to zero, we will have,

\[
\delta S = \delta\alpha \left( \int_{t_1}^{t_2} [t_1 dx - t_2 dx] \right) = 0
\]

(18)

\[
\delta S = \delta\beta \left( \int_{t_1}^{t_2} [t_1 dx - t_2 dx] \right) = 0
\]

(19)

\[
\delta S = \delta t_1 \left( 2[y(t_1) - \alpha - \beta t_1] = 0 \right)
\]

(20)

\[
\delta S = \delta t_2 \left( -2[y(t_2) - \alpha - \beta t_2] = 0 \right)
\]

(21)

Equations (18) through (21) may be solved simultaneously for \(\alpha, \beta, t_1\) and \(t_2\). Thus, we have the following system of equations,

\[
2t_2 - 2t_1 - 1 = 0
\]

(22)

\[
t_2^2 - t_1^2 - \frac{1}{2} = 0
\]

(23)

\[
y(t_1) - \alpha - \beta t_1 = 0
\]

(24)

\[
y(t_2) - \alpha - \beta t_2 = 0
\]

(25)

The solutions are,

\[
t_1 = \frac{1}{4}
\]

(26)

\[
t_2 = \frac{3}{4}
\]

(27)

\[
\alpha = y(3/4)-(3/4)\beta = y(1/4)-(1/4)\beta
\]

(28)

\[
\beta = 2[y(3/4)-y(1/4)]
\]

(29)

This procedure, similar to that of multiple regression model for discrete case may be expanded to include "m" unknown parameters which is not discussed here. Some computational methods for solving the different cases of m parameters model are investigated by Ptak (1958), Rice and White (1964), Rice (1964a,b,c,69,85), Usow (1967a), Lazarski (1975a,b,c,77) (see also, Hobby and Rice (1965), Kripke and Rivlin (1965), Watson (1981)). Now, let us have a look at Lorenz curve and its proposed functional forms.

5. Lorenz curve

The Lorenz curve for a random variable with probability density function \(f(v)\) may be defined as the ordered pair\(^2\),

\(^2\) Taguchi (1972a,b,c,73,81,83,87,88) multiplies the second element of (30) by \(P(V|V\leq v)\) which is not correct; his definition of (31) is equivalent to ours.
\[
\frac{E(V|V \leq v)}{P(V|V \leq v), \frac{E(V)}{v} \in \mathbb{R}}
\] (30)

Where "P" and "E" stand for probability and expected value operators. For a continuous density function \( f(v) \), (30) can be written as,

\[
\int_{-\infty}^{v} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} w f(w) dw = (x(v), y(x(v)))
\] (31)

We denote (31) by \((x(v), y(x(v)))\) where \(x(v)\) and \(y(x(v))\) are its elements. Therefore, "x" is a function which maps "v" to \(x(v)\) and "y" is a function which maps \(x(v)\) to \(y(x(v))\). The function \(y(x(v))\) is simply the Lorenz curve function. In recent years some functional forms for Lorenz curve have been introduced. Among different proposed functions we use the forms of Gupta (1984) and Bidabad and Bidabad (1989,92) which benefits from certain properties (see their articles for more explanations). Gupta (1984) proposed the functional form,

\[y = xA^{x-1} \quad A > 1\] (32)

Bidabad and Bidabad (1989,92) suggest the following functional form:

\[y = xBA^{x-1} \quad B > 1, A \geq 1\] (33)

To estimate the above functions by regular estimating method, we should gather discrete data from the statistical population, and manipulate them to construct relevant \(x\) and \(y\) vectors to estimate "A" of (32) or "A" and "B" of (33). If the probability distribution of income is known, instead of gathering discrete observations, we can estimate the Lorenz curve by using the continuous \(L_1\) norm smoothing method for continuous functions. In the following section we proceed to apply this method to estimate the parameters "A" of (32) and "A" and "B" of (33) by using the information of probability density function of income.

6. Continuous \(L_1\) norm smoothing of Lorenz curve

To estimate the Lorenz curve parameters when income probability density function is known, we can not always take straightforward steps. When the probability density function is easily integrable, there is no major problem in advance. We can find the functional relationship between the two elements of (31) by simple mathematical derivation. But, when integrals of (31) are not obtainable, another procedure should be adopted.

Suppose that income of a society is distributed with probability density function \( f(w) \). This density function may be a skewed function such as Pareto or log-normal, as follows

\[f(w) = \theta k \theta w - 0 - 1, \quad \text{wrk} > 0, \theta > 0\] (34)

\[f(w) = \frac{1}{w \sigma \sqrt{(2 \pi)}} \exp \left\{ \frac{[-\ln(w) - \mu]^2}{2 \sigma^2} \right\}, \quad \text{we} (0, \infty), \mu \in (-\infty, +\infty), \sigma > 0\] (35)

These two distributions have been known as good candidates for presenting distribution of personal income.

In the case of Pareto density function of (34), we can simply derive the Lorenz curve function as follows. Let \( F(w) \) denote the Pareto distribution function:

\[F(w) = 1 - (k/w)^\theta\] (36)

with mean equal to,

\[E(w) = \theta^\theta/(\theta - 1), \quad \theta > 1\] (37)
If we find the function $y$ as stated by (31) as a function of $x$, the Lorenz function will be derived. Now, proceed as follows. Rearrange the terms of (31) as,

$$
x(v) = \int_{-\infty}^{v} f(w)dw
$$

$$
y(x(v)) = \left[1/E(x)v\right] \int_{-\infty}^{v} w f(w)dw
$$

Substitute Pareto distribution function,

$$
x(v) = F(v) = 1-(k/v)^\theta
$$

$$
y(x(v)) = \left[\frac{(\theta-1)/(\theta^2)}{k}\right] \int_{v}^{\infty} w \theta k^\theta w^{-\theta-1}dw
$$

or, 

$$
y(x(v)) = 1-(k/v)^{\theta-1}
$$

Now, by solving (40) for "v" and substituting in (42), the Lorenz curve for Pareto distribution is derived as,

$$
y = 1-(1-x)^{\theta-1}\theta
$$

As it was shown in the case of Pareto distribution, formula of Lorenz curve is easily obtained. But, if we select the log-normal density function (35), the procedure may not be the same. Because the integral of log-normal function has not been derived yet. In the following pages, the $L_1$ norm smoothing technique will be developed to estimate the parameters of given functional forms (32) and (33) by using the continuous probability density function.

According to (30) and (31) independent and dependent variables of (32) and (33) may be written as,

$$
x(v) = \int_{0}^{v} f(w)dw
$$

$$
y(x(v)) = \left[1/E(x)v\right] \int_{0}^{v} w f(w)dw
$$

Substitute (44) and (45) inside (32) and define random error term $u$ as,

$$
\left[1/E(w)\right] \int_{0}^{v} w f(w)dw = \int_{0}^{v} f(w)dw.A . e^u
$$

or briefly,

$$
y(x)=xA^{x-1}e^u
$$

Similarly for the model (35),

$$
\left[1/E(w)\right] \int_{0}^{v} w f(w)dw = \int_{0}^{v} f(w)dw.B . A . e^u
$$

or briefly,

$$
y(x)=xA^{x-1}e^u
$$

Taking natural logarithm of (47) and (49), gives,

$$
\ln y(x) = \ln x + (x-1)\ln A + u
$$

$$
\ln y(x) = B.\ln x + (x-1)\ln A + u
$$

With respect to properties of Lorenz curve and probability density function of $f(w)$ and equations (46) to (49), it is obvious that $x$ belongs to the interval $[0,1]$. Thus the $L_1$ norm objective function for minimizing (50) or (51) is given by,
\[
\min: S = \int_0^1 |u| \, dx
\]

Now, let us deal with $L_1$ norm estimation of "A" of Lorenz curve functional form (32) (redefined by (50)). The corresponding $L_1$ norm objective function will be,

\[
\min: S = \int_0^1 |\ln y(x) - \ln x - (x-1) \ln A| \, dx
\]

or,

\[
\min: S = \int_0^1 |x-1||\ln y(x)-\ln x|/(x-1) - \ln A| \, dx
\]

By a similar technique used by (9), we can rewrite (54) as,

\[
\min: S = \int_0^1 |x-1|{\left[\frac{\ln y(x)-\ln x}{(x-1)}-\ln A\right]} \, dx
\]

or,

\[
\min: S = \int_0^1 |x-1|{\left[\frac{\ln y(x)-\ln x}{(x-1)}-\ln A\right]} \, dx
\]

Differentiate (56) partially with respect to "t" and "A" and equate them to zero;

\[
\frac{\partial S}{\partial t} = + \int_0^t \left[\frac{1}{A}\right] \, dx - \int_0^1 \left[\frac{1}{A}\right] \, dx = 0
\]

\[
\frac{\partial S}{\partial A} = - 2\left[\ln y(t) - \ln t - (t-1) \ln A\right] = 0
\]

From equation (57), we have,

\[
t = 1\pm\sqrt{2}/2
\]

Since "t" should belong to the interval $[0,1]$, we accept,

\[
t = 1-\sqrt{2}/2
\]

Substitute (60) in (58), and solve for "A", gives the $L_1$ norm estimation for "A" equal to,

\[
A = \left[\frac{1-\sqrt{2}/2}{y(1-\sqrt{2}/2)}\right]^{1/2}
\]

Now, let us apply this procedure to another Lorenz curve functional form of (33) (redefined by (51)). Rewrite $L_1$ norm objective function (52) for the model (51),

\[
\min: S = \int_0^1 \ln y(x) - B \ln x - (x-1) \ln A| \, dx
\]

or,

\[
\min: S = \int_0^1 |x-1||\ln y(x)-(x-1)-(\ln x)/(x-1)-\ln A| \, dx
\]

The objective function (63) - by some changing on variables - is similar to (16). Thus, by a similar procedure to those of (17) through (29) we can write "S" as,
\[
\begin{align*}
\min: \; S &= \int_0^{t_1} \left[ \frac{\ln y(x)}{x-1} - \frac{\ln x}{x-1} - \ln A \right] dx \\
A, B

- \int_{t_1}^{t_2} \left[ \frac{\ln y(x)}{x-1} - \frac{\ln x}{x-1} - \ln A \right] dx \\
+ \int_{t_2}^{1} \left[ \frac{\ln y(x)}{x-1} - \frac{\ln x}{x-1} - \ln A \right] dx
\end{align*}
\]

(64)

Since \(0 \leq x \leq 1\), then (64) reduces to,
\[
\begin{align*}
\min: \; S &= - \int_0^{t_1} \left[ \ln y(x) - B \ln x - (x-1) \ln A \right] dx + \int_{t_1}^{t_2} \left[ \ln y(x) - B \ln x - (x-1) \ln A \right] dx \\
A, B

- \int_{t_2}^{1} \left[ \ln y(x) - B \ln x - (x-1) \ln A \right] dx
\end{align*}
\]

(65)

Differentiate "S" partially with respect to "A", "B", \(t_1\) and \(t_2\) and equate them to zero,
\[
\begin{align*}
\frac{\delta S}{\delta A} &= \int_{t_1}^{t_2} \left[ \frac{1}{0 \ln x} - \frac{1}{(x-1) \ln A} \right] dx = 0 \\
\frac{\delta S}{\delta B} &= \int_{t_1}^{t_2} \left[ \frac{1}{\ln x} - \frac{1}{\ln A} \right] dx = 0 \\
\frac{\delta S}{\delta t_1} &= -2 \left[ \ln [y(t_1)] - B \ln (t_1) - (t_1-1) \ln (A) \right] = 0 \\
\frac{\delta S}{\delta t_2} &= 2 \left[ \ln [y(t_2)] - B \ln (t_2) - (t_2-1) \ln (A) \right] = 0
\end{align*}
\]

(66) 
(67) 
(68) 
(69)

The above system of simultaneous equations can be solved for the unknowns \(t_1\), \(t_2\), "A" and "B". Equation (66) is reduced to,
\[
t_1^2 - t_2^2 - 2(t_1 - t_2) - 1/2 = 0
\]

(70)

Equation (67) can be written as,
\[
t_1(\ln t_1 - 1) - t_2(\ln t_2 - 1) - 1/2 = 0
\]

(71)

Calculate \(t_1\) from (70) as,
\[
t_1 = 1 \pm \sqrt{q \left( t_2^2 - 2t_2 + 3/2 \right)}
\]

(72)

Since \(0 \leq t_1 \leq 1\), we accept,
\[
t_1 = 1 - \sqrt{t_2^2 - 2t_2 + 3/2}
\]

(73)

Substitute \(t_1\) from (73) into (71), and rearrange the terms, gives;
\[
\frac{\ln \left[ 1 - \sqrt{t_2^2 - 2t_2 + 3/2} \right]}{t_2^2} + \frac{t_2 - 3/2 + \sqrt{t_2^2 - 2t_2 + 3/2}}{t_2^2} = 0
\]

(74)

The root of equation (74) may be computed by a suitable numerical algorithm. However, it has been computed and rounded for five digits decimal point as,
\[
t_2 = 0.40442
\]

(75)
Value of $t_1$ is derived by substituting $t_2$ into (73):

$$t_1 = 0.07549 \quad (76)$$

Values of "B" and "A" are computed from (68) and (69) using $t_2$ and $t_1$ given by (75) and (76). Thus,

$$B = \frac{(t_2-1)\ln(y(t_1)) - (t_1-1)\ln(y(t_2))}{(t_2-1)\ln(t_1) - (t_1-1)\ln(t_2)} \quad (77)$$

or,

$$B = -0.84857\ln[y(0.07549)] + 1.31722\ln[y(0.40442)] \quad (78)$$

and,

$$A = [y(0.07549)]^{1.28986}[y(0.40442)]^{-3.68126} \quad (79)$$

Now, let us describe how equation (61) for the model (32) and equations (78) and (79) for the model (33) can be used to estimate the parameters of the Lorenz curve when the probability distribution function is known. In the model (32) we should solve (44) for $x(v) = 1 - \frac{x^2}{2}$. On the other hand, we should find value of "v" such that,

$$\int_v^0 f(w)dw = 1 - \frac{x^2}{2} \quad (80)$$

By substituting this value of "v" into (45), value of $y(1 - \sqrt{2}/2)$ is computed. The value $y(1 - \sqrt{2}/2)$ is used to compute the parameter "A" given by (61) for model (32).

The procedure for the model (33) is also similar, with the difference that two values of "v" should be computed. Once two different values of "v" are computed as follow,

$$x(v) = \begin{cases} \int_v^0 f(w)dw = 0.07549 \\ \int_v^0 f(w)dw = 0.40442 \end{cases} \quad (81, 82)$$

Values of "v" are substituted in (45) to find $y(0.07549)$ and $y(0.40442)$. These values of "y" are used to compute the parameters of the model (33) by substituting them into (78) and (79).

The only problem remains is computation of related definite integrals of $x(v)$ defined by (80), (81) and (82) which can be done by appropriate numerical methods such as the enclosed sample computer program coded for MathCAD 11 for a complete example.

### 7. Income distribution in Iran

In order to compute the Lorenz curve for Iran we try to apply the above procedure for both (32) and (33) propositions and using log-normal distribution function assumption. The source of data is "Statistical Center of Iran" who computed the mean and variance of income for urban and rural families for the period of 1362-1370 (1983-1991) from "Family Budget Surveys" of different years. These data are given by table 1. The amount of mean and variance of income were used to derive the log-normal density function parameters $\mu$ and $\sigma$. The explained procedure of estimation then applied to the series of data of table 1, and corresponding results are reported in table 2. A sample computer program is also enclosed at the end of these pages.
<table>
<thead>
<tr>
<th>Year</th>
<th>Sample size</th>
<th>Income Mean</th>
<th>Income variance</th>
<th>Sample size</th>
<th>Income Mean</th>
<th>Income variance</th>
</tr>
</thead>
<tbody>
<tr>
<td>1362</td>
<td>14747</td>
<td>91842</td>
<td>1106199</td>
<td>12440</td>
<td>471942</td>
<td>192638591017</td>
</tr>
<tr>
<td>1363</td>
<td>14728</td>
<td>1034169</td>
<td>1174389</td>
<td>12420</td>
<td>524623</td>
<td>351371674839</td>
</tr>
<tr>
<td>1364</td>
<td>13976</td>
<td>1037084</td>
<td>1792475</td>
<td>13587</td>
<td>531098</td>
<td>301917047049</td>
</tr>
<tr>
<td>1365</td>
<td>2745</td>
<td>1126638</td>
<td>1300389</td>
<td>3015</td>
<td>568557</td>
<td>404222563256</td>
</tr>
<tr>
<td>1366</td>
<td>2748</td>
<td>1147497</td>
<td>1410976</td>
<td>3018</td>
<td>710145</td>
<td>491696298459</td>
</tr>
<tr>
<td>1367</td>
<td>3987</td>
<td>1360121</td>
<td>2551576</td>
<td>4331</td>
<td>908530</td>
<td>174305631712</td>
</tr>
<tr>
<td>1368</td>
<td>5492</td>
<td>1505970</td>
<td>4786980</td>
<td>6028</td>
<td>1052371</td>
<td>101959722471</td>
</tr>
<tr>
<td>1369</td>
<td>9095</td>
<td>2010471</td>
<td>1258790</td>
<td>9348</td>
<td>1251060</td>
<td>552912735060</td>
</tr>
<tr>
<td>1370</td>
<td>9168</td>
<td>2840790</td>
<td>6695871</td>
<td>9504</td>
<td>1563116</td>
<td>750567996872</td>
</tr>
</tbody>
</table>

Source: Statistical Center of Iran.

<table>
<thead>
<tr>
<th>Year</th>
<th>Gupta Model</th>
<th>Bidabad Model</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>A</td>
<td>Gini</td>
</tr>
<tr>
<td>Urban estimation</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1362</td>
<td>7.259</td>
<td>0.430</td>
</tr>
<tr>
<td>1363</td>
<td>6.279</td>
<td>0.409</td>
</tr>
<tr>
<td>1364</td>
<td>8.915</td>
<td>0.457</td>
</tr>
<tr>
<td>1365</td>
<td>5.943</td>
<td>0.401</td>
</tr>
<tr>
<td>1366</td>
<td>6.158</td>
<td>0.407</td>
</tr>
<tr>
<td>1367</td>
<td>7.574</td>
<td>0.436</td>
</tr>
<tr>
<td>1368</td>
<td>11.021</td>
<td>0.482</td>
</tr>
<tr>
<td>1369</td>
<td>15.841</td>
<td>0.522</td>
</tr>
<tr>
<td>Rural estimation</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1370</td>
<td>42.211</td>
<td>0.605</td>
</tr>
<tr>
<td>1362</td>
<td>5.220</td>
<td>0.382</td>
</tr>
<tr>
<td>1363</td>
<td>7.099</td>
<td>0.427</td>
</tr>
<tr>
<td>1364</td>
<td>6.152</td>
<td>0.406</td>
</tr>
<tr>
<td>1365</td>
<td>6.978</td>
<td>0.424</td>
</tr>
<tr>
<td>1366</td>
<td>5.718</td>
<td>0.396</td>
</tr>
<tr>
<td>1367</td>
<td>11.025</td>
<td>0.482</td>
</tr>
<tr>
<td>1368</td>
<td>5.472</td>
<td>0.389</td>
</tr>
<tr>
<td>1369</td>
<td>17.955</td>
<td>0.534</td>
</tr>
<tr>
<td>1370</td>
<td>15.683</td>
<td>0.521</td>
</tr>
</tbody>
</table>
References

- Bidabad B. (1987a) Least absolute error estimation. Submitted to the First International Conference on Statistical Data Analysis Based on the L₁ norm and Related Methods, Neuchatel, Switzerland.
- Bidabad B. (1987b) Least absolute error estimation, part II. Submitted to the First International Conference on Statistical Data Analysis Based on the L₁ norm and Related Methods, Neuchatel, Switzerland.
- Ptak V. (1958) On approximation of continuous functions in the metric \( \|x(t)\|_{L_1} \). Czechoslovak Math. J. 8(83), 267-273.